

# DC-Micromotors

## Precious Metal Commutation

2,9 mNm  
5,3 W

### Series 1524 ... SR

Values at 22°C and nominal voltage	1524 T	003 SR	006 SR	009 SR	012 SR	018 SR	024 SR	
1 Nominal voltage	$U_N$	3	6	9	12	18	24	V
2 Terminal resistance	$R$	1,1	5,1	10,6	19,8	43,9	79,3	$\Omega$
3 Efficiency, max.	$\eta_{max}$	80	80	80	80	80	80	%
4 No-load speed	$n_0$	10 600	9 500	10 000	9 800	9 800	9 800	min <sup>-1</sup>
5 No-load current, typ. (with shaft $\varnothing$ 1,5 mm)	$I_0$	0,03	0,013	0,009	0,007	0,005	0,004	A
6 Stall torque	$M_H$	6,95	6,98	7,18	6,92	7,07	6,91	mNm
7 Friction torque	$M_R$	0,08	0,08	0,08	0,08	0,08	0,08	mNm
8 Speed constant	$k_n$	3 577	1 592	1 117	827	548	414	min <sup>-1</sup> /V
9 Back-EMF constant	$k_E$	0,28	0,628	0,895	1,21	1,83	2,42	mV/min <sup>-1</sup>
10 Torque constant	$k_M$	2,67	6	8,55	11,5	17,4	23,1	mNm/A
11 Current constant	$k_I$	0,374	0,167	0,117	0,087	0,057	0,043	A/mNm
12 Slope of n-M curve	$\Delta n / \Delta M$	1 530	1 350	1 380	1 420	1 380	1 420	min <sup>-1</sup> /mNm
13 Rotor inductance	$L$	22	110	230	420	950	1 670	$\mu$ H
14 Mechanical time constant	$\tau_m$	8,5	8,2	8,3	8,3	8,2	8,3	ms
15 Rotor inertia	$J$	0,53	0,58	0,57	0,56	0,57	0,56	gcm <sup>2</sup>
16 Angular acceleration	$\alpha_{max}$	131	120	126	124	124	123	$\cdot 10^3$ rad/s <sup>2</sup>
17 Thermal resistance	$R_{th1} / R_{th2}$	10 / 29						K/W
18 Thermal time constant	$\tau_{w1} / \tau_{w2}$	5,6 / 220						s
19 Operating temperature range:								
– motor		-30 ... +85 (optional version -55 ... +125)						°C
– winding, max. permissible		+125						°C
20 Shaft bearings		sintered bearings (standard)			ball bearings, preloaded (optional version)			
21 Shaft load max.:								
– with shaft diameter		1,5			1,5			mm
– radial at 3 000 min <sup>-1</sup> (3 mm from bearing)		1,2			5			N
– axial at 3 000 min <sup>-1</sup>		0,2			0,5			N
– axial at standstill		20			10			N
22 Shaft play:								
– radial	$\leq$	0,03			0,015			mm
– axial	$\leq$	0,2			0			mm
23 Housing material		steel, black coated						
24 Mass		18						g
25 Direction of rotation		clockwise, viewed from the front face						
26 Speed up to	$n_{max}$	13 000						min <sup>-1</sup>
27 Number of pole pairs		1						
28 Magnet material		NdFeB						
<b>Rated values for continuous operation</b>								
29 Rated torque	$M_N$	1,7	2,9	2,9	2,9	2,9	2,9	mNm
30 Rated current (thermal limit)	$I_N$	0,7	0,56	0,38	0,28	0,19	0,14	A
31 Rated speed	$n_N$	7 800	3 860	4 500	4 130	4 330	4 110	min <sup>-1</sup>

**Note:** Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The  $R_{th2}$  value has been reduced by 0%.

#### Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ( $R_{th2}$  50% reduced).

The nominal voltage ( $U_N$ ) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



